

1 Land water contribution to sea level from GRACE
2 and Jason measurements

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Abstract. We investigate the effect of water storage changes in the world's major hydrological catchment basins on global and regional sea level change at seasonal and long-term time scales. In a joint inversion using GRACE and Jason-1 data we estimate the time-dependent [sea level](#) contributions of 124 [spatial patterns](#) ('fingerprints') including glacier and ice-sheet melting, thermal expansion, changes in the terrestrial hydrological cycle and glacial isostatic adjustment. Particularly, for hydrological storage changes we derive fingerprints of the 33 world's largest catchment basins, assuming mass distributions derived from the leading EOFs of total water storage in the WaterGap Global Hydrological Model (WGHM). [From our inversion](#), we estimate a contribution of terrestrial hydrological cycle changes to global mean sea level of -0.20 ± 0.04 mm/yr with an annual amplitude of 6.6 ± 0.5 mm for 08/2002 to 07/2009. Using only GRACE data in the inversion and comparing to hydrological changes derived from GRACE data directly using a basin averaging method shows a good agreement on a global scale, but considerable differences are found for individual catchment basins (up to 180%). Hydrological storage change estimates in 33 basins from the GRACE/Jason fingerprint inversion indicate a trend 46% smaller and an annual amplitude 43% bigger compared to WGHM-derived storage changes. [Mapping the hydrological trends to](#) regional sea level reveals the strongest sea level rise along the coastlines of South America (max. 0.9 mm/yr) and West Africa (max. 0.4 mm/yr), whereas around Alaska and Australia we find the hydrological component of sea level falling (min. -2.0 mm/yr and -0.9 mm/yr).

1. Introduction

26 The IPCC 4th assessment report (IPCC-AR4, *Bindoff et al. [2007]*) identified sea level
27 change as one of the most important environmental problems for the coming century.
28 Global mean sea level has been observed to rise by 3.4 ± 0.4 mm/yr over the last two
29 decades [*Cazenave and Llovel, 2010*], while regional sea level increases by up to three
30 times this number and even falls in some places [*Slangen et al., 2012*]. Though predictions
31 for regional sea level exhibit considerable variance, it is expected that many low-lying
32 countries will face ecological and economical difficulties associated with sea level rise in
33 the future. Many coastal regions will be affected by for example submergence of land,
34 frequent flooding, saltwater intrusion of surface waters, and increased erosion [*Nicholls*
35 *and Cazenave, 2010*].

36 Understanding and quantifying the individual sources that contribute to global mean
37 sea level and regional sea level change is therefore crucial. Ocean warming, an observed
38 melting of (parts of) the large ice sheets and glaciers, and land subsidence due to glacial
39 isostatic adjustment (GIA) all contribute to [absolute](#) sea level changes [as observed by](#)
40 [satellite altimetry](#). In addition, variability in the terrestrial hydrological cycle affects sea
41 level through net run-off and surface flux changes.

42 Understanding hydrological variability is particularly important since a large share of it
43 is believed to be caused by anthropogenic activity, i.e. groundwater pumping, irrigation,
44 and reservoir construction. In the IPCC-AR4 the hydrological changes are not included
45 in the estimate of the various contributions to the budget of global mean sea level change.
46 As the discrepancy between the sum of estimated contributions and the observed sea level

47 change is according to this report 0.3 ± 1.0 mm/yr for 1993-2003, land water storage
48 changes are assumed to be small (< 0.5 mm/yr) or compensated for by unaccounted
49 or underestimated contributions. However, the contribution from terrestrial hydrological
50 changes is likely one of the least well-known contributions in the sea level budget and
51 reducing its uncertainty is an important task in order to find an explanation for the
52 discrepancy between observed and estimated sea level change.

53 Estimates of changes in terrestrial hydrology can be derived from hydrological models
54 by solving the water balance equation. For example, *Milly et al.* [2003] use the Land
55 Dynamics (LaD, *Milly and Shmakin* [2002]) model to calculate a small positive sea level
56 trend of about 0.12 mm/yr corresponding to land water storage over 1981 - 1998 and
57 0.25 mm/yr for 1993-1998. By running the ORCHIDEE model over five decades (1948
58 - 2000) *Ngo-Duc et al.* [2005] find no significant trend but a strong decadal variability
59 of about 2 mm in amplitude. For other time periods, they derive trends of 0.08 mm/yr
60 (1981-1998) and 0.32 mm/yr (1972-1993). Anthropogenic effects are difficult to model
61 due to data scarcity, but studies indicate that these may play an important role [*Fiedler*
62 *and Conrad*, 2010]. For example, *Chao et al.* [2008] estimate that from dam impoundment
63 alone the sea level could have decreased by 0.55 mm/yr in the last half of the past century.
64 On the other hand, *Konikow* [2011] finds a positive sea level trend of 0.4 mm/yr due to
65 groundwater depletion for 2000 - 2008. A somewhat stronger trend of 0.57 ± 0.09 mm/yr
66 due to groundwater depletion is diagnosed for the year 2000 by *Wada et al.* [2012]. In this
67 study it is suggested that groundwater depletion may dominate the terrestrial hydrological
68 contribution to sea level change in future, leading to a net land water contribution of
69 0.87 ± 0.14 mm/yr by 2050. Sea level changes due to anthropogenic impacts on terrestrial

70 water storage are also estimated by *Pokhrel et al.* [2012] for 1961 - 2003 to be 0.77 mm/yr
71 (1.05 mm/yr from groundwater depletion, -0.39 mm/yr from dam impoundment, 0.08
72 mm/yr from climate-driven changes in terrestrial water storage and 0.03 mm/yr from the
73 Aral Sea).

74 Since the launch of the GRACE (Gravity Recovery And Climate Experiment) satel-
75 lites in March 2002, land mass changes can be directly observed. By reducing superim-
76 posed mass signals (melting of glaciers, glacial isostatic adjustment GIA, atmospheric and
77 oceanic variations), terrestrial hydrological cycle changes can be assessed with GRACE.
78 For example, *Ramillien et al.* [2008] applied a basin averaging method to filtered GRACE
79 Release 3 monthly solutions from the GeoForschungsZentrum Potsdam (GFZ). By con-
80 sidering 27 of the world's largest river basins, they rate the terrestrial hydrological con-
81 tributions to global mean sea level to 0.19 ± 0.06 mm/yr. Using the same method but
82 with GRACE Release 4 data provided by three processing groups (GFZ, Jet Propulsion
83 Laboratory JPL, and Center for Space Research at the Texas University CSR), an ex-
84 tended time period (2002 - 2009), and considering 33 river basins, *Llovel et al.* [2010]
85 estimated the terrestrial hydrological contribution to sea level change to be slightly neg-
86 ative (-0.22 ± 0.05 mm/yr, i.e. more water is deposited on land). Finally *Riva et al.*
87 [2010] assess the total ice and water mass loss from land (including Greenland, Antarctica
88 and glaciers) contributing to 1.0 ± 0.4 mm/yr over the years 2003-2009. Of this, they
89 conclude that the net impact of terrestrial hydrology adds (or rather subtracts) a small
90 rate of -0.1 ± 0.3 mm/yr to global mean sea level, but that it dominates regional sea level
91 change in coastal regions.

92 There are several reasons for the observed differences in the estimated land water storage

93 changes. Whereas in the hydrological models the water storage changes for the entire land
94 area (with Greenland and Antarctica excluded) are considered, *Ramillien et al.* [2008] and
95 *Llovel et al.* [2010] only estimate the contribution of the 27 and 33, respectively, largest
96 river basins. In doing so, areas with strong non-hydrological signals (e.g. glacier melting)
97 which cannot be easily separated from the hydrological signals can be excluded from the
98 estimate. However, since only 43% of the continental surface is covered by those basins,
99 part of the hydrological signal may be neglected. **On the other hand, when GRACE-**
100 **derived mass changes of the entire land surface are compared to hydrological model re-**
101 **sults, the contribution of glacier melting (usually not part of the model) has to be taken**
102 **into account.** In addition, differences between the estimates derived from GRACE obser-
103 vations may be due to different data releases, different background models (e.g. GIA) and
104 different filtering procedures. Furthermore, due to the strong interannual and decadal
105 variability of water storage, computed trends are strongly dependent on the time period
106 considered and cannot be directly compared. On the other hand, hydrological models are
107 sensitive to errors in forcing fields and water use data. As in particular trends are often
108 not well captured in these data [*Fiedler and Döll, 2007; Vörösmarty and Sahagian, 2000*],
109 modelled terrestrial hydrological cycle trends may be quite uncertain.

110 In theory, one could try to remove all other modelled or observed contributions to global
111 mean sea level or regional sea level from the sea level change as observed by radar-
112 altimetric satellite missions, in order to solve for the contribution of the terrestrial hydro-
113 logical cycle. This residual approach, however, proves difficult as considerable uncertain-
114 ties are associated with all other contributions as well [*Milne et al., 2009; Chambers and*
115 *Schröter, 2011*]. The same holds for conventional basin averaging approaches performed

116 on GRACE data, in which all superimposed mass signals have to be removed prior to
117 analysis. In the present contribution, we provide a new estimate for land water contri-
118 butions to global and regional sea level rise based upon data from the GRACE mission
119 and the Jason-1 altimeter satellite. Like *Llovel et al.* [2010], we consider the 33 world's
120 largest hydrological catchment basins. We use a fingerprint method first suggested by
121 *Plag and Jüttner* [2001] in the context of tide gauge data analysis which is based on the
122 assumption that the large-scale sea level patterns of the major sources of sea level change
123 can be well-modelled using physical relations except for a time-variable magnitude, that
124 determines the actual sea level contribution of the source. To assess these magnitudes we
125 combine temporal gravity and altimetry data in a joint least squares inversion. Whereas
126 the fingerprints are pre-defined and assumed to be time-invariant, the gravity and altime-
127 try data is (solely) used to estimate the time-series of scaling factors for the fingerprints,
128 and not for determining the spatial pattern. In contrast to other observation-based esti-
129 mates, we jointly assess all contributions (including the steric effect) to sea level change
130 and therefore do not rely on models of superimposed signals to be removed. Another ad-
131 vantage of our method is that filtering and rescaling of the GRACE data, a major source
132 of uncertainty in GRACE-derived mass changes, can be avoided. We demonstrate this by
133 applying our method to GRACE data only (without considering altimetry data) and com-
134 paring to results obtained with a conventional GRACE basin averaging approach. We also
135 compare our results to water storage changes from the WaterGAP Global Hydrological
136 Model (WGHM, *Döll et al.* [2003]) both on basin and continental scale. Furthermore, we
137 use the fingerprint inversion to map the regional sea level change caused by water storage
138 changes in the 33 largest basins and estimate the impact on the three largest ocean basins.

139 This paper is organized as follows: In section 2 we describe the three methods - hydro-
140 logical modelling, GRACE basin averaging and the fingerprint inversion - which we use
141 to derive the terrestrial hydrological cycle change estimates. The used data and prepro-
142 cessing steps are specified in section 3. In section 4 we discuss our results with emphasis
143 on the contribution of the 33 largest catchment basins to global mean sea level change
144 obtained with different methods and the regional sea level change. In section 5 we draw
145 the conclusions from our results and address future work.

2. Methods

2.1. Hydrological modelling

146 Sea level contributions caused by terrestrial hydrological changes can be evaluated using
147 land surface models or global hydrological models. In-situ measurements of groundwater
148 levels and other hydrological storage systems are temporally and spatially sparse, and
149 may be biased when collected in areas where the water table is locally lowered due to
150 irrigation. Models are forced by meteorological data and aim at realistic physical or
151 conceptual process representation, transfer of energy, lateral and vertical flux of water,
152 and anthropogenic water use. They may be calibrated against gauged runoff. When
153 aggregated over vertical compartments and grid cells or catchments, mass conservation
154 states that the change of mass over land, $\frac{dM}{dt}$, originates from the net effect of precipitation,
155 P , evaporation, E and runoff, R :

$$\frac{dM}{dt} = P - E - R. \quad (1)$$

157 However, biases in observed forcing fields, deficiencies in model realism and physical
158 parametrization, and missing information on water consumption, irrigation, reservoir

159 building and other factors may render long-term storage change and aggregated runoff
160 unrealistic. In this work, we assume that the right-hand side of Eq. (1) reaches the ocean
161 immediately [*Peixoto and Oort, 1992*], and that it adapts itself to an equipotential sur-
162 face. With other words, on the spatial and temporal scales considered here, changes of
163 the amount of water stored in the atmosphere will be neglected as well as dynamic effects
164 of ocean circulation.

2.2. GRACE basin averaging

165 GFZ Potsdam, JPL, CSR, and a number of other groups provide time-dependent Stokes'
166 coefficients $c_{nm}(t)$, $s_{nm}(t)$ derived from GRACE observations. From these, one can derive
167 surface mass variations $\frac{dM}{dt}$ using methods described for example in *Wahr et al. [1998]*
168 and thus compute the left-hand side of Eq. (1). Usually, the temporal resolution is one
169 month. Since GRACE cannot separate between different sources of mass variability, all
170 non-hydrological signals (atmosphere, ocean, glaciers, GIA) have to be reduced from the
171 data in order to isolate the hydrological mass variations. Moreover, the spatial resolution
172 of the GRACE-derived mass variations is limited to about 300 km due to the altitude of
173 the satellites and the accuracy of the microwave ranging instrument. Therefore realistic
174 terrestrial hydrological mass variations can only be estimated as an average for basins
175 larger than about 90000 km².

176 For higher spherical harmonic degrees, the GRACE coefficients are strongly affected by
177 correlated errors, which cause characteristic north-south directed artifacts in the spatial
178 domain. Hence, to derive realistic mass variations, filtering of the monthly solutions is
179 necessary. Usually a spectral decorrelation followed by a spatial smoothing is applied
180 [*Swenson and Wahr, 2006; Kusche, 2007*]. Filtering the GRACE data reduces noise but

181 it also leads to an amplitude attenuation of the signal and external mass signals leaking
182 into the averaging area (leakage-in). The amplitude attenuation is often compensated for
183 by rescaling the mass variations with a constant factor (e.g., *Velicogna and Wahr [2006]*).
184 However, as the true mass distribution and thus the true attenuation is unknown, the
185 determination of the rescaling factor always involves assumptions [*Kusche, 2007; Klees*
186 *et al., 2008; Fenoglio-Marc et al., 2012*]. There exist several methods for reducing the
187 leakage-in caused by external mass variations, which also involve their own assumptions
188 [*Baur et al., 2009; Longuevergne et al., 2010*]. Handling these two effects is one of the
189 major source of uncertainties in GRACE-derived basin averages.

190 To obtain regional sea level changes, the computation of sea level fingerprints is required.
191 Assuming a normalized load distribution in the basin and applying the sea level equation
192 (e.g. appendix A1) to it leads to a spatial sea level pattern, which is - scaled with the
193 GRACE basin average - an estimate for regional sea level changes. A similar approach,
194 pursued by *Riva et al. [2010]*, is to derive global maps of mass trends from GRACE data
195 and use these as the input load for the sea level equation.

2.3. Fingerprint inversion from GRACE

196 The idea of our fingerprint inversion is that the total (observed) sea level change pat-
197 tern consists largely of a sum of characteristic spatial patterns of sea level change caused
198 by individual mass sources $M_{(i)}(\lambda, \theta)$. It is assumed that these fingerprints can be cal-
199 culated a priori up to an unknown time-dependent magnitude for each fingerprint. By
200 combining gravity and altimetry data the magnitudes can be estimated. In contrast to
201 mascon approaches [*Rowlands et al., 2010*], where patterns are defined on a (regular) grid,
202 our fingerprints result from the physical delineation of a limited number of independent

203 regions and their individual mass distribution. In our current approach, the fingerprints
204 are assumed to remain constant over time, merely the scaling factor (magnitude) is time-
205 variable. Ocean model simulations may be used in future to constrain the time scales
206 where this working hypothesis is valid [*Brunnabend et al., 2011*].

207 The fingerprints can be calculated in terms of sea level but also in terms of the associated
208 gravitational potential. Thus we assume that the total gravitational potential observed
209 by GRACE consists of a sum of characteristic spatial patterns of gravitational potential
210 scaled with the same (to be solved for) magnitudes as the corresponding sea level fin-
211 gerprints. Whereas the fingerprints for different mass sources have to be calculated by
212 using the full sea level equation, involving gravitational-elastic response and rotational
213 feedback [*Rietbroek et al., 2011*], their magnitudes (i.e. the scaling factors), are solved-for
214 parameters of the inversion. They can be estimated by fitting the Stokes' coefficients $c_{nm}^{(i)}$,
215 $s_{nm}^{(i)}$ that we derive from the pre-computed fingerprints to the GRACE-derived Stokes' co-
216 efficients by means of a least squares inversion. In order to consider only signals of global
217 mean sea level contributors, atmospheric signals have been removed from the GRACE
218 data in advance.

219 When fitting the relatively large-scale fingerprints to the GRACE level-2 data in terms
220 of potential no further smoothing or destriping of the GRACE coefficients is required.
221 Using GRACE level-2 data, we estimate magnitudes $x(t)$ of the fingerprints for ice sheet
222 (Greenland, Antarctica) basins, a set of clusters of glaciers, hydrological catchments (in-
223 cluding lakes and groundwater contributions) and an a priori chosen global GIA pattern

224 by solving

$$225 \quad \delta\Phi(t) = A \begin{pmatrix} x_{ice} \\ x_{glac} \\ x_{hydro} \\ x_{gia} \end{pmatrix} (t) + e(t), \quad (2)$$

226 where $\delta\Phi(t)$ are the (stacked) Stokes' coefficients measured by GRACE. Columns of the
 227 design matrix A contain the Stokes' coefficients $c_{nm}^{(i)}$, $s_{nm}^{(i)}$ of the fingerprints and the vector
 228 $e(t)$ represents the GRACE errors and the 'ommission' error of variability not explained
 229 by our set of source patterns. We then set up normal equations with normal matrix, N_G
 230 and right hand side, n_G :

$$231 \quad N_G(t) = A^T C_G^{-1}(t) A \quad n_G(t) = A^T C_G^{-1}(t) \delta\Phi(t) \quad (3)$$

232 where $C_G^{-1}(t)$ is the inverse error covariance matrix of the GRACE Stokes' coefficients
 233 $\delta\Phi(t)$. As the GRACE Stokes' coefficients $\delta\Phi(t)$ already represent the solution of the
 234 original GRACE normal equations

$$235 \quad \delta\Phi(t) = (N^*)^{-1}(t) n^*(t) \quad (4)$$

236 (to which we have access), the inverse error covariance matrix in (3) is given by $C_G^{-1}(t) =$
 237 $N^*(t)$. With other words, our normal equations follow from a re-parametrization of the
 238 GRACE normal equations,

$$239 \quad N_G(t) = A^T N^*(t) A \quad n_G(t) = A^T n^*(t). \quad (5)$$

240 Before solving for $x(t)$ the normal equations can be modified. The temporal resolution of
241 the resulting time series can be stabilized by accumulating several normal equations. As
242 in this study we are mainly interested in trend and seasonal variations of mass changes,
243 we modified the normal equations by inserting parameters for trend and annual sine and
244 cosine wave amplitudes for each fingerprint and accumulating all normal equations in the
245 time period August 2002 until July 2009.

246 Within the fingerprint method small neighboring basins cannot be separated, because they
247 exhibit very similar fingerprints. However, in contrast to the GRACE basin averaging
248 method, here we obtain correlations for the mass variations between the different basins
249 and thus get information about dependencies of basin mass estimates. Due to the coarse
250 GRACE spatial resolution, one has to limit the set of patterns or base functions to those
251 of larger spatial extent and avoid near rank defects in an inverse scheme as suggested
252 here. On the other hand, patterns of mass flux or sea level change that we disregard in
253 the inversion, such as ocean circulation changes, water storage changes outside of the 33
254 basins or individual glaciers, may bias our results depending on their degree of spatial
255 non-orthogonality with respect to the patterns that are modelled. This 'representation
256 error' effect has a similar nature as the leakage-in problem in a basin averaging approach.

2.4. Fingerprint inversion from GRACE and Jason-1

257 Several years ago, *Plag and Jüttner* [2001] suggested to use tide gauge observations
258 of sea level in a fingerprint inversion approach. Similarly, radar altimetric missions al-
259 low measuring global sea level directly. However, altimetric sea level also contains steric
260 height changes and a component due to the dynamic ocean circulation. The consistent
261 separation of sources of sea level change therefore calls for combining the two observation

262 techniques GRACE and altimetry [*Rietbroek et al.*, 2011].

263 We may relate the fingerprint magnitudes $x(t)$ to the Jason-1 along-track sea level anoma-
 264 lies $\delta h(t)$ by

$$265 \quad \delta h(t) = B \begin{pmatrix} x_{ice} \\ x_{glac} \\ x_{hydro} \\ x_{gia} \\ x_{ster} \end{pmatrix} (t) + e(t) \quad (6)$$

266 similar to Eq. (2). Matrix B contains in its columns the normalized fingerprints evaluated
 267 at the measurement locations. The vector $e(t)$ accounts for altimeter noise (range and
 268 correction errors) and ocean variability beyond a 'passive' ocean response [*Blewitt and*
 269 *Clarke*, 2003]. From the Jason-1 data, we set up a second system of normal equations

$$270 \quad N_J(t) = B^T C_J^{-1}(t) B \quad n_J(t) = B^T C_J^{-1}(t) \delta h(t) \quad (7)$$

271 weighted by the matrix $C_J(t)$ containing the Jason-1 errors. Equations (7) are then
 272 combined with the normal equations obtained from GRACE observations (Eq.(5)) and
 273 subsequent inversion provides the fingerprint magnitudes for all contributors to sea level
 274 change. Combining GRACE and Jason is useful, since the nullspace of the combination
 275 is smaller than the nullspace of each technique. E.g., *Rietbroek et al.* [2011] determined
 276 secular geocenter motion from this combination (see also *Wu et al.* [2012]).

277 At present $C_G(t)$ in equation (3) and $C_J(t)$ in equation (7) are modelled to represent
 278 instrumental errors only and are considered thus both too optimistic. In future research
 279 we will try to assess more realistic weighting which will include assessing unmodelled vari-

280 ability and omission errors. Whereas $C_G(t)$ is derived from the full GRACE covariance
281 matrix and therefore takes into account spatial correlations, the errors in $C_J(t)$ are calcu-
282 lated from the standard deviations of the 20 Hz satellite observations and no correlations
283 are considered.

3. Data

3.1. WGHM data

284 In this study, we use global, monthly variations of total water storage (TWS) derived
285 from the WaterGAP Global Hydrological Model (WGHM, *Döll et al.* [2003]). WGHM
286 simulates the terrestrial water cycle by implementing conceptual formulations of the most
287 important hydrological processes and includes all storage compartments relevant for de-
288 scribing vertical and lateral mass redistribution. The model is forced by ECMWF climate
289 data (temperature, cloudiness, number of rain days) and GPCC monthly precipitation
290 data [*Rudolf and Schneider, 2005*], and calibrated against gauged runoff. It has been
291 used in many GRACE-related studies and has been calibrated against GRACE by *Werth*
292 *and Güntner* [2010]. Furthermore, specific model versions exist that consider updated
293 anthropogenic water use [*Döll et al., 2011*], improved floodplane dynamics [*Adam et al.,*
294 2010], or higher spatial resolution ($5' \times 5'$, *aus der Beek et al.* [2011]). Here, we use
295 $0.5^\circ \times 0.5^\circ$ output fields of WGHM provided by *Döll et al.* [2011], with the long-term
296 average TWS removed to obtain anomalies comparable to GRACE results. Unrealistic
297 values and trends have been observed in some regions (for example in Greenland), but
298 these are not included in our inventory of the largest 33 basins.

3.2. GRACE data

299 For the basin averaging method, we use GRACE Release 4 Level 2 monthly solutions
300 provided by GFZ Potsdam for the time period July 2002 to August 2009, given in form of
301 Stokes' coefficients up to degree and order 120 [Flechtner, 2007]. The monthly solutions
302 are reduced for atmospheric and oceanic signals using standard Atmosphere and Ocean
303 De-aliasing Level-1B (AOD1B) products. As is well-known, degree 1 coefficients related
304 to geocenter motion cannot be observed from GRACE range rates. However, as the
305 individual precomputed fingerprints contain contributions from the degree 1 coefficients,
306 the fingerprint inversion from GRACE provides a time-series of degree 1 coefficients by
307 which we augment the GRACE monthly solutions before using them in the basin averaging
308 approach. Moreover, in the GRACE Release 4 monthly solutions the c_{20} coefficient is
309 affected by ocean tidal aliasing and exhibits large non-geophysical variations. Therefore
310 we replace c_{20} with an external time-series derived from SLR measurements [Cheng and
311 Tapley, 2004]. Then, we remove the average of the monthly solutions over the whole time-
312 period to obtain anomalies. Before averaging over the basins we destripe the monthly
313 solutions by applying the anisotropic DDK3 filter [Kusche, 2007]. We account for the
314 effect of GIA by subtracting a model by Klemann and Martinec [2009] which uses the
315 ICE-5G ice history and VM2 rheology [Peltier, 2004], and which is given in spherical
316 harmonic coefficients up to degree and order 64.

317 For the fingerprint inversion method, we use weekly GRACE Release 4 normal equations
318 from GFZ Potsdam complete up to degree and order 150 [Dahle et al., 2008], processed
319 with the same standards as the monthly solutions. In order to be consistent with altimetry
320 data, the weekly AOD1B products as well as rates in the c_{20} and c_{40} coefficients are

321 restored. However, to be consistent with the IB-correction from altimetry, we do not
322 restore the ocean average of the atmospheric pressure over the ocean [*Leuliette and Miller,*
323 2009]. The weekly GRACE normal equations do not contain degree 1 coefficients. In
324 contrast to the basin averaging method, we do not use external time-series for degree 1
325 coefficients within the fingerprint inversion method, as these can be estimated [*Rietbroek*
326 *et al.*, 2011]. Furthermore, there appears no need for filtering or smoothing the weekly
327 GRACE normal equations in the fingerprint inversion method because the GRACE data
328 do not provide the spatial patterns of mass variations but are rather projected onto the
329 'fingerprint space'.

3.3. Jason-1 data

330 The Jason-1 [*Chambers et al.*, 2003] data is obtained from the Open Altimeter Database
331 (OpenADB, *Schwatke et al.* [2010]). The altimeter ranges in this database were interpo-
332 lated to predefined bins which are located alongtrack and are fixed in time and space.
333 The size of the bins corresponds to the length of the path that the satellite ground track
334 covers in one second, i.e. about 5.8 km. [OpenADB data is corrected for several geophys-](#)
335 [ical and atmospheric effects: the EOT11a model is used for ocean and loading tides, and](#)
336 [a dynamic atmospheric correction based on AVISO products using the Mog2D model for](#)
337 [high frequencies and an inverse barometer correction for the lower frequencies is applied.](#)
338 [Dry troposphere effects are corrected using reanalysis data from the European Centre for](#)
339 [Medium-range Weather Forecast \(ECMWF\), whereas the wet troposphere effect is de-](#)
340 [rived from the radiometer data of the satellite. Jason-1 orbits refer to the EIGEN-GL04c](#)
341 [gravity field model and are expressed in the ITRF2005 reference frame. Radial orbit](#)
342 [errors are derived from comparing multi-mission altimetry \(MMXO12 cross calibration\).](#)

343 We did not apply a GIA correction to the altimeter data, since we include it within the
344 fingerprint inversion where the GIA contribution is estimated together with other sea level
345 contributions.

346

3.4. Steric data

347 In this study, the steric sea level contribution is estimated indirectly in the fingerprint
348 inversion by combining Jason-1 and GRACE data. To separate steric from mass induced
349 sea level changes we calculate fingerprints not only for the mass contributions but also for
350 the steric contributions. The steric fingerprints are derived from gridded in-situ data from
351 Argo floats, bouys and CTD casts: we use a dataset from *Hosoda et al.* [2008] who provide
352 monthly global 1° grids of steric sea level height. Since the Argo data (temperature and
353 salinity) are collected up to a maximum depth of 2000 m, the contribution of possible
354 deep ocean warming is not contained in the datasets. We perform a Principle Component
355 Analysis (PCA) on the monthly grids for the time period 01/2001 to 10/2010, and the
356 first 30 Empirical Orthogonal Functions (EOFs) are then used as steric fingerprints in the
357 inversion. These 30 EOFs contain about 87% of the total signal. To summarize, we would
358 like to emphasize that in this study we do not use the Argo data directly to quantify the
359 steric sea level contribution but only derive the spatial patterns from these data, while the
360 magnitudes of the patterns are indirectly estimated by combining altimetry and GRACE
361 in the fingerprint inversion.

4. Results

4.1. Global sea level change from 33 basins

362 For this study, we consider the 33 largest river basins of the world (Fig. 1). Their
363 outlines are based on masks with 0.5° resolution from *Oki and Sud* [1998]. Analysis of the
364 WGHM water storage shows that these basins nevertheless capture only 48% of the annual
365 amplitude and 74% of the trend of the total hydrological signal represented by the model.
366 However, the regions not covered by these 33 largest basins are mainly regions which are
367 either known to exhibit small storage changes (North Africa, Arabian Peninsula, Western
368 Australia), contain glaciers (e.g. Patagonia, Himalaya), or are highly affected by GIA
369 uplift (Fennoscandia, Canada). Since models of glacier mass loss and GIA are subject to
370 large uncertainties [*Cogley*, 2009; *Guo et al.*, 2012], basin averages of hydrological changes
371 obtained from GRACE in those regions will be highly uncertain. Although in principle
372 the fingerprint inversion method should allow to better distinguish superimposed signals
373 as long as they are related to different spatial patterns, here we use only the 33 basins in
374 order to be comparable with the GRACE basin averaging results.

375 4.1.1. Results from the GRACE basin averaging

376 The GRACE basin averages for the time period August 2002 to July 2009 are computed
377 in the spectral domain by converting the basin masks into spherical harmonic coefficients
378 and accumulating the product of these coefficients with the filtered GRACE coefficients,
379 converted to equivalent water height (EWH) following *Wahr et al.* [1998]. To account
380 for an amplitude attenuation [*Klees et al.*, 2008] due to filtering, we rescaled the monthly
381 averages with a factor, which we compute separately for each basin: We convert a uniform
382 basin mass distribution into spherical harmonic coefficients and filter them with the same
383 filter as applied to the GRACE coefficients. The scaling factors - the ratio of the average
384 basin mass before and after filtering - range between 1.08 and 1.75. The trends, phases and

385 annual amplitudes obtained for the terrestrial hydrological mass change with the GRACE
386 basin averaging (in the following abbreviated as *BasAv*) after rescaling are shown in
387 column 3 (*BasAv*) of table 1 and 2. For the phase we indicate the month in the year
388 when the maximum of the annual variation is reached.

389 Three main error sources add to the uncertainty of these values: the choice of the filter,
390 the choice of the GIA model (only influencing the trend) and the GRACE measurement
391 errors. To account for the error introduced by filtering and rescaling, we compute the
392 total terrestrial hydrological trend, annual amplitude and phase from GRACE monthly
393 solutions with five different filters (DDK1, DDK2, DDK3, Gaussian 300km, Gaussian
394 500km). Each time series is rescaled corresponding to the filter that was used. By
395 comparing, we obtain RMS values of 9.9 Gt/yr for the trend, of 212.2 Gt for the annual
396 amplitude, and of 0.03 months for the phase. We compare the contribution of four different
397 GIA models [*Klemann and Martinec*, 2009; *Spada and Stocchi*, 2007; *Wang et al.*, 2008;
398 *Wu et al.*, 2010] to mass change in the region covered by all 33 basins and find a RMS
399 of 12.7 Gt/yr adding to the uncertainty of the trend. The uncertainty due to GRACE
400 errors propagated from the calibrated errors of the GRACE monthly solutions is found
401 to be 3.3 Gt/yr, 28.3 Gt and 0.02 months for trend, amplitude and phase, respectively.
402 Thus, these three error levels yield the error bars finally given in tables 1 and 2 for the
403 total values.

404 4.1.2. Results from the GRACE-only fingerprint inversion

405 Within the fingerprint inversion method, we precompute 124 fingerprints: 16 finger-
406 prints for Greenland drainage basins, 31 fingerprints for Antarctica drainage basins, 13
407 fingerprints for clusters of major glacier systems (from the World Glacier Inventory WGI,

408 *NSIDC* [1999]), 33 river basin fingerprints for the terrestrial hydrological cycle, 1 fin-
409 gerprint for the GIA contribution, and 30 fingerprints for the steric contribution. The
410 fingerprints are calculated as follows: For the mass contributions, we use the sea level
411 equation [Farrell and Clark, 1976] to derive mass consistent fingerprints in terms of sea
412 level and in terms of gravitational potential, see also appendix A1. We normalize the
413 mass load used in the sea level equation for each source to 1 Gt. In particular, the 33 ter-
414 restrial hydrological fingerprints are derived by applying the sea level equation assuming
415 a uniform mass change in each of the largest river basins. For the GIA pattern we use the
416 same model by Klemann and Martinec [2009] as considered in the GRACE basin averag-
417 ing. As described in section 3.4 for the steric sea level patterns, we perform a Principal
418 Component Analysis (PCA) of gridded products derived from Argo and other in-situ data
419 [Hosoda et al., 2008] and use the first 30 EOFs as steric 'fingerprints' [Rietbroek et al.,
420 2011].

421 As mentioned above, to separate the effect of methodology (fingerprint inversion vs. basin
422 averaging) from the sensitivity with respect to the added altimetry data, we first performed
423 a fingerprint inversion with only GRACE data (below referred to as *InvGR*). In this case,
424 we did not incorporate the steric fingerprints. Although it is theoretically possible in the
425 fingerprint inversion from GRACE to estimate a scaling factor for the GIA model, here
426 we fixed this factor to 1.0 in order to be consistent with the basin averaging method.
427 By augmenting the weekly normal equations of the fingerprint inversion by trend and
428 sine/cosine wave parameters for each fingerprint, and adding up all normal equations for
429 the considered time period, we estimate the values for the terrestrial hydrological cycle
430 changes listed in column 4 (*InvGR*) of table 1 and 2. Uncertainties for these values are

431 obtained from the formal inversion errors scaled with the a posteriori variance; however
432 they appear to be underestimated by about a factor of 10 compared to the errors of the
433 GRACE basin averaging.

434 The total terrestrial hydrological cycle trends and annual amplitudes obtained with the
435 two methods (basin averaging and fingerprint inversion from GRACE data only) differ by
436 14.4% and 4.1%, respectively and agree within their standard deviations. The absolute
437 phase difference is found to be 0.05 months. However, the relative difference of the trends
438 for individual basins can be quite large (maximum 171.1% for Danube, minimum 0.2% for
439 St. Lawrence). The mean relative difference is 62.5% for the trend and 33.9% for the am-
440 plitude. The RMS of the phase differences is rather small, only 0.29 months. Analysis of
441 the relative differences for individual basins showed that the magnitude of the differences
442 depends neither on the basin size nor on the geographical latitude of the basin. Compar-
443 ing the trends accumulated to the continental scale (table 3) shows that big differences
444 mainly occur in the North American and Eurasian basins, where large glaciers and GIA
445 signals are superimposed to hydrological signals. Whereas in the inversion method the
446 mass variations of glaciers are simultaneously estimated and correlations can be evalu-
447 ated, they are not considered in the basin averaging method. Another difference in the
448 methods is the filtering of the GRACE data, which is omitted in the inversion method.
449 On the other hand in the basin averaging method, no predefined information about the
450 spatial pattern of the mass variations is used, whereas in the inversion we assume the
451 mass variations to be uniform in each hydrological basin, which is likely not the case for
452 large basins.

453 **4.1.3. Results from the combined GRACE/Jason-1 fingerprint inversion**

454 Column 5 (*Inv*) of table 1 and 2 shows the results of the combined GRACE and Jason-
455 1 fingerprint inversion, i.e. with using GRACE and Jason-1 normal equations and co-
456 estimating the magnitudes for the steric fingerprints. For better comparison with the
457 GRACE-only fingerprint inversion, we still set the GIA factor to 1.0 and use uniform mass
458 distribution for the calculation of the basin fingerprints. Somewhat surprisingly, introduc-
459 ing Jason-1 data causes a sizeable effect on the estimated total trend of the hydrological
460 basins (difference 71.9% between *InvGR* and *Inv*), whereas amplitude and phase do not
461 change much (difference 3.1% and 0.10 months). Interestingly, the other mass-related
462 contributors to global mean sea level change (Greenland, Antarctica, Glaciers) are much
463 less affected by adding the altimetry data. Whereas the terrestrial hydrological cycle
464 trends obtained with different inversion schemes exhibit a global mean sea level stan-
465 dard deviation of 0.066 mm/yr, trends for Greenland, Antarctica and the Glaciers result
466 with standard deviations of only 0.003, 0.010 and 0.038 mm/yr, respectively. This phe-
467 nomenon is currently being investigated. Relative differences of individual basin trends,
468 amplitudes and phases with respect to the basin averaging method are similar to those
469 from the GRACE-only inversion (69.2% and 32.5% in average for trend and amplitude,
470 respectively; 0.05 months for the phase).

471 As mentioned above, the mass change in the hydrological basins is not uniform as as-
472 sumed in the results discussed so far. Using a more realistic mass distribution might thus
473 reduce the trend differences of the basins between the two methods. To study this effect,
474 we calculated fingerprints from the leading EOFs (Empirical Orthogonal Functions) of
475 each basin's WGHM output maps. Using these fingerprints in the combined inversion
476 instead of those produced from uniform mass distributions we estimate a total trend of

54.1 Gt/yr for the terrestrial hydrological cycle (not shown in table 1 and 2) which is closer to the *BasAv* and the *InvGR* solutions than the terrestrial hydrological trend of the *Inv* solution. However, the mean relative difference of the basins (70.6%) did not improve. The reason might be that the leading EOFs, pointing in the direction of maximum variability of the data, may not be well suited to represent trends. Strikingly, the trend of the Amazon basin is found much smaller (only 39.8 Gt/yr) than estimated from the other solutions (101.9, 82.7 and 67.2 Gt/yr, respectively). The annual amplitude of the Amazon basin is also smaller for the solution using hydrology EOFs than for the others (1086.8 Gt vs. 1171.0, 1312.5, and 1306.1 Gt respectively). The Amazon basin might be too big to be well described in its spatial mass change variability by only one EOF. In fact, the Amazon basin is nearly twice as big (6.23×10^6 km²) as the largest of the other basins (Congo, 3.76×10^6 km²) we considered. Using two hydrological EOF-fingerprints for the Amazon basin in the inversion (and one EOF for the other basins) leads to a trend and amplitude of the Amazon basin (66.7 Gt/yr and 1207.0 Gt) that are closer to those of the other solutions while the other basins are nearly unaffected. The results of this inversion are shown in column 6 (*InvEOF*) of table 1 and 2. In this solution, we also co-estimated a scaling factor of 0.97 for the GIA pattern instead of fixing it to 1.0 which is well within the spread of current GIA models. The total terrestrial hydrological cycle trend is now similar to the GRACE-only trend (*InvGR*) and it is 16.1% smaller than the hydrological trend of the *BasAv* solution, while the amplitudes of the two solutions differ by only 1.4% with an absolute phase difference of 0.06 months.

As mentioned above, error estimates obtained with the inversion method are probably too optimistic. As an upper boundary for the errors of trend, amplitude and phase, we cal-

500 culate the standard deviations of the results from the different inversion setups in table 1
501 and 2 to 31.3 Gt/yr, 48.0 Gt and 0.06 months, respectively. Whereas for amplitude and
502 phase this seems to be realistic, for the trend it appears too pessimistic in comparison to
503 the *BasAv* errors. Being conservative, we scale the errors from the inversion by a factor
504 of 10 in order to match the magnitude of the *BasAv* errors.

505 4.1.4. Results from the WGHM

506 For comparison, we also computed the trends, annual amplitudes and phases of the
507 terrestrial hydrological mass change for the time period August 2002 to July 2009 from
508 WGHM alone. The results are shown in column 7 of table 1 and 2, respectively. Whereas
509 the total terrestrial hydrological trend obtained from the WGHM is 45.9% larger than the
510 *BasAv* trend, the seasonal amplitude is 43.2% smaller. We also find a sizeable absolute
511 phase difference of 1.17 months. Differences compared to the trends estimated within
512 the inversion are even bigger, up to 87.0%. The relative differences of individual basin
513 trends between the WGHM and the *BasAv* solution can reach up to 148.6% and the
514 average difference is 79.4%. For the amplitude, the maximal relative difference is 77.6%
515 with an average difference of 44.5%. Absolute phase differences range from 0.1 to 4.2
516 months for the individual basins with an RMS of 0.27 months. Other authors also found
517 significant discrepancies between mass changes derived from GRACE and from WGHM
518 [*Werth and Güntner, 2010; Forootan et al., 2012*]. Comparing the terrestrial hydrological
519 trends on a continental scale (table 3) shows that the main differences occur in North
520 America and Australia. In North America a strong GIA signal exists, which is present
521 in the GRACE data but not in WGHM. For Australia *Forootan et al.* [2012] found that
522 the correlation between GRACE-derived and WGHM-derived TWS from 2003 to 2010 is

523 significantly lower than for a regional hydrological model. In particular, in the Southeast
524 of Australia (location of Murray and Lake Eyre basin) they found a correlation with the
525 WGHM of mostly below 0.2. This corresponds to part of the differences between WGHM
526 and GRACE-derived terrestrial hydrological cycle trends we find.

527 **4.1.5. Contributions to global mean sea level from the fingerprint inversion**

528 For our reference inversion using GRACE and Jason-1 observations, EOF hydrology
529 fingerprints (two for the Amazon basin) and freely co-estimating a GIA scaling factor,
530 we estimate a total terrestrial hydrological cycle mass trend of 74.7 ± 13.6 Gt/yr with
531 an annual amplitude of 2442.6 ± 204.0 Gt. We consider this our most realistic estimate.
532 This positive mass trend corresponds to a small negative contribution to global mean sea
533 level change of -0.20 ± 0.04 mm/yr for the period August 2002 to July 2009. The annual
534 amplitude is estimated to be 6.6 ± 0.5 mm. However, all terrestrial hydrological cycle
535 trend results are strongly dependent on the time period considered. Taking four different
536 time periods (08/2002 - 07/2009, 01/2003 - 12/2009, 08/2003 - 07/2010, and 01/2004 -
537 12/2010), using the same inversion setup we found the total terrestrial hydrological cycle
538 trends ranging from -9.3 Gt/yr to 92.8 Gt/yr with a standard deviation of 48.2 Gt/yr.
539 The annual amplitude is only marginally affected (2442.6 Gt to 2542.5 Gt, standard
540 deviation of 41.8 Gt). The terrestrial hydrological cycle exhibits strong interannual and
541 decadal variations [*Ngo-Duc et al.*, 2005; *Llovel et al.*, 2010]. The sensitivity of the trend
542 estimates to different time periods is a result of these decadal variations. For Greenland,
543 West Antarctica and glaciated regions the interannual and decadal mass variability is
544 smaller compared to the annual and long-term signal, thus the sensitivity to the time
545 period is less pronounced.

546 For our reference fingerprint inversion (using one/two EOF WGHM fingerprints and co-
547 estimating the GIA-scale, *InvEOF* in table 1 and 2), using GRACE and Jason-1 data, we
548 calculate the global mean sea level contributions given in column 2 of table 4. To enable
549 a consistent comparison of the total sea level trend from the fingerprint inversion and the
550 total sea level trend obtained from Jason-1 data, we provide in column 3 of table 4 the
551 mean sea level trend for each contributor confined to latitudes between 66° north and 66°
552 south, as the altimeter data also does not cover the high latitudes. The GIA contribution
553 is however kept constant for both columns, since it can be considered as a globally uniform
554 offset of the altimetry data. The altimeter is sensitive to GIA related changes in ocean
555 basin volume, regardless of its data coverage. For 08/2002 to 07/2008 we obtain from the
556 fingerprint inversion a global mean sea level trend of 1.56 mm/yr and from the Jason-1
557 data a trend of 1.94 mm/yr which leaves 0.38 mm/yr that cannot be explained in the
558 inversion to be due to glacier or ice sheet mass loss, terrestrial hydrological changes, GIA
559 or thermal expansion. The Greenland contribution of 0.63 ± 0.008 (-232.9 ± 0.3 Gt/yr)
560 lies within the range of estimates other authors made for similar time periods (*Ewert et al.*
561 [2012], -191.2 ± 20.9 Gt/yr for 08/2002 to 06/2009, *Velicogna* [2009], -230 ± 33 Gt/yr for
562 04/2002 to 02/2009, *Schrama et al.* [2011] -201 ± 19 Gt/yr for 03/2003 to 02/2010). The
563 contribution of Antarctica 0.26 ± 0.014 (-94.5 ± 0.5 Gt/yr) is found to be significantly
564 smaller than the Greenland contribution. This is confirmed in other studies (*Horwath*
565 *and Dietrich* [2009], -109 ± 48 Gt/yr for 08/2002 to 01/2008, *Velicogna* [2009], -143 ± 73
566 Gt/yr for 04/2002 to 02/2009). Estimates for the total contribution of glacier ice melting
567 to global mean sea level cover a relatively wide range. In the IPCC-AR4 it is assumed to
568 be 0.77 ± 0.22 mm/yr for 1993 to 2003, whereas *Cogley* [2009] find a value nearly twice

569 that big (1.4 ± 0.2 mm/yr) for 2001 to 2005. However, a recent study by *Jacob et al.* [2012]
570 estimated the glacier contribution to global mean sea level to be only 0.41 ± 0.08 mm/yr
571 for 2003 to 2010. Thus our estimate of 0.58 ± 0.027 mm/yr indeed confirms a rate at the
572 lower end of the published spectrum of estimates. The estimates of the steric and GIA
573 contribution estimate of 0.35 ± 0.022 mm/yr and -0.16 ± 0.003 are also consistent with
574 results from other authors [*Cazenave and Llovel, 2010; Guo et al., 2012*]. Our estimate
575 for the contribution of the terrestrial hydrological cycle is discussed in section 5.

4.2. Regional sea level change

576 By converting the basin EOF fingerprints, scaled from the inversion, to the spatial do-
577 main we obtain a global map of regional sea level trend and annual amplitude caused by
578 terrestrial hydrological cycle mass changes, which is shown in figure 2. According to our
579 results, mainly the coastal areas of South America as well as the western coast of Africa
580 are affected by a relevant sea level rise due to land water contributions. In the Amazon
581 river delta the trend reaches values up to 0.9 mm/yr, while in the Congo river delta the
582 maximum trend is 0.4 mm/yr. In contrast, the North American coastal area, especially
583 around Alaska, is subject to falling sea level. The minimum of the trend in this area is
584 -2.0 mm/yr in the Gulf of Alaska. However, it is unclear to what extent the strong neg-
585 ative regional sea level trend is really caused by hydrological mass changes or by glacier
586 mass loss in the same area. In fact, from the covariance matrix of the inversion a rather
587 strong negative correlation of -0.55 between the Yukon basin trend and the Brooks Range
588 glaciers in Northern Alaska is found. The correlation of the Yukon basin with the glaciers
589 at the Gulf of Alaska is -0.42 . Figure 2 also suggests a sea level fall of minimal -0.9
590 mm/yr around Australia due to mass loss in the Lake Eyre and Murray river basin in the

591 considered time period. Eurasia is only marginally affected by sea level variations due to
592 terrestrial hydrological cycle mass changes.

593 The annual amplitude shown in figure 2 exhibits for most parts of the northern hemi-
594 sphere amplitudes below the global mean of 6.6 mm, whereas in the southern hemisphere
595 amplitudes slightly higher than the global mean are predominant. Lower amplitudes in
596 the northern hemisphere are due to the fact that the annual cycle of water mass storage
597 on the northern continents reaches its maximum in mid-March, causing a gravitational
598 attraction of ocean water masses which is nearly 180° out of phase to the globally averaged
599 cycle of ocean water mass (maximum in mid-October). In short, a damping of the am-
600 plitude occurs. Analogously, the amplitude increases where the continental mass storage
601 cycle is in phase with the global mean ocean mass cycle. This effect is especially large
602 around South America (with amplitudes down to 1 mm) and Southeast Asia (with am-
603 plitudes up to 20 mm) where strong annual mass amplitudes in the Amazon and Mekong
604 basin due to seasonal Monsoon rainfall occur. Depending on the phase of the continental
605 signal, the sea level amplitude is reduced (Amazon) or amplified (Mekong).

606 Finally, in table 5 we average estimated regional hydrological sea level trends and ampli-
607 tudes over the three largest ocean basins (Atlantic, Pacific and Indian Ocean, boundaries
608 depicted in figure 1). Not surprising, the terrestrial hydrological cycle trend is negative
609 for each basin but for the Atlantic Ocean it is about four times smaller compared to the
610 Pacific and Indian ocean and about 70% smaller compared to the global mean hydrolog-
611 ical sea level trend. The sea level trends in the Pacific and Indian ocean are 23% and
612 17% larger than the global mean. These relations are quite robust against using differ-
613 ent setups in the inversion. Thus, although the total terrestrial hydrological cycle trends

614 differ depending on the inversion setup, the spatial distribution is similar. The annual
615 amplitude is found largest for the Indian Ocean, about 14% higher than the amplitude of
616 the global mean hydrological sea level amplitude. For the Pacific Ocean the annual am-
617 plitude is only slightly larger (5%) than the global mean, whereas for the Atlantic Ocean
618 the amplitude is about 16% smaller.

5. Conclusions

619 Using GRACE and Jason-1 data from the time period of August 2002 to July 2009 in
620 an inverse fingerprint method, we find that land water storage change from the world's 33
621 largest hydrological basins contributes to global sea level change by -0.20 ± 0.04 mm/yr
622 with an annual amplitude of 6.6 ± 0.5 mm. To study the effect of using different methods,
623 we apply our inversion method to GRACE data only and compare the results to the trends
624 and amplitudes derived from GRACE with a basin averaging method. While we find con-
625 siderable differences between the methods for individual catchments (up to 180%), results
626 are quite robust in terms of global and regional sea level change. The major differences
627 occur in North America and Eurasia, which we believe is due to GIA and glacier melting
628 effects treated differently in the methods. In addition, in the fingerprint inversion, we do
629 not need to filter the GRACE data and rescale the mass change estimates as we do in the
630 basin averaging approach.

631 We have investigated the sensitivity of the fingerprint inversion method with respect to
632 the data set (GRACE, GRACE and Jason-1), to the choice of the a-priori fingerprint mass
633 distribution (uniform, leading EOFs from model) and to the treatment of GIA (fixed a-
634 priori or scaled by estimated factor). Depending on the chosen setup, the total terrestrial
635 hydrological cycle trend varies in a range of 21.6 ± 14.8 Gt/yr to 76.8 ± 14.0 Gt/yr, how-

636 ever, the seasonal amplitude variations are only small. Furthermore, the estimated total
637 terrestrial hydrological cycle trend strongly depends on the time period considered, which
638 is due to large interannual and decadal hydrological variations.

639 The spatial distribution of trend and annual amplitude for the sea level change due to ter-
640 restrial hydrological cycle mass changes is fairly robust with respect to different inversion
641 setups. It displays a sea level rise around South America (max. 0.9 mm/yr) and West
642 Africa (max. 0.4 mm/yr), and a sea level fall around North America (min. -2.0 mm/yr)
643 and Australia (min. -0.9 mm/yr).

644 The inversion results indicate that they may be useful in improving the WGHM model
645 in terms of seasonal amplitude and trend. Whereas in earlier model-based studies [*Milly*
646 *et al.*, 2003; *Ngo-Duc et al.*, 2005] the contribution of terrestrial hydrological cycle mass
647 changes to global mean sea level change was assumed to be slightly positive, in more
648 recent studies based on GRACE data [*Llovel et al.*, 2010; *Riva et al.*, 2010] it was rather
649 found to be negative in the same order of magnitude. This might be due to the differ-
650 ent time frames considered. In this study we also find a small negative contribution of
651 terrestrial hydrological cycle mass changes to global mean sea level change. Our estimate
652 of -0.20 ± 0.04 mm/yr agrees well with the result of *Llovel et al.* [2010] (-0.22 ± 0.05
653 mm/yr), who used the same time period and the same hydrological basins. When we
654 analyse the same time period that *Riva et al.* [2010] chose, i.e. January 2003 to Decem-
655 ber 2009, we obtain a terrestrial hydrological cycle-driven global mean sea level change
656 of -0.24 ± 0.04 which is also within the error bounds of the value of *Riva et al.* [2010]
657 (-0.1 ± 0.3 mm/yr). Not surprisingly, we also find the [hydrological cycle-driven](#) regional
658 sea level change to be dominant in the coastal areas. Our spatial pattern of regional sea

659 level trend is similar to the one of *Riva et al.* [2010], but the strong positive sea level trend
660 these authors found for most of Northern Eurasia is much smaller in our results, which
661 might be due to a different GIA model. The pattern of annual amplitude is quite close to
662 the sea level amplitude pattern *Wouters et al.* [2011] derive from GRACE for continental
663 water mass changes by solving the 'sea level equation'. However, as *Wouters et al.* [2011]
664 consider mass changes from the whole land surface (not only from 33 hydrological basins)
665 they find a larger global ocean mean amplitude of 9.4 ± 0.6 mm and (due to not excluding
666 glaciers) lower amplitudes in the high latitudes compared to our results.

667 Future work will address improving our data base of a priori mass patterns we use in
668 the inversion. The world's largest hydrological basins, in terms of surface area, are not
669 necessarily those basins that contribute most to the terrestrial hydrological cycle trend
670 and amplitude. By choosing other and possibly more hydrological basins, our estimate
671 may become more robust. Furthermore, we plan to use more than one pattern for the
672 GIA in order to adjust different regions of past glaciation (Laurentide, Fennoscandia,...)
673 independently within the inversion. This requires a tradeoff since similar (in particu-
674 lar neighboring) patterns render the inversion unstable. Therefore, introducing formal
675 constraints might be necessary. In addition, deep-ocean steric fingerprints from ocean
676 circulation models could further help to explain observed sea level change.

Appendix A: Calculation of sea level fingerprints

A1. Sea level equation

677 The sea level fingerprints for the mass contributors to global mean sea level change are
678 obtained in this study by solving the sea level equation [*Farrell and Clark*, 1976], which
679 links the sea level change $\delta s(\lambda, \theta, t)$ at a location with longitude λ and colatitude θ at a

680 time t with a continental mass load $\delta h(\lambda', \theta', t)$, expressed in equivalent water heights

$$\begin{aligned}
 681 \quad \delta s(\lambda, \theta, t) = O(\lambda, \theta) \int_{\Omega} G_{N-U}^L (\delta s(\lambda', \theta', t) + \delta h(\lambda', \theta', t)) d\omega \\
 682 \quad \quad \quad + \int_{\Omega} G_{N-U}^T \delta \Lambda(\delta s, \delta h) d\omega + \frac{\Delta V}{g}. \tag{A1}
 \end{aligned}$$

683 Within Eq. (A1) we consider (a) gravitational effects of the mass load (b) gravitational
 684 effects of the sea level itself and (c) changes of the rotational potential $\delta \Lambda$ due to the
 685 changed surface loading distribution. The Green's functions G_{N-U}^L and G_{N-U}^T describe
 686 the elastic response of the Earth to a point-like, impulse mass load (index L) and to
 687 general potential forcing (index T), respectively. They are given in terms of the difference
 688 between the geoid N and the associated uplift U [Farrell, 1972]. As $\delta s(\lambda, \theta, t)$ is only
 689 defined over the ocean, the ocean function $O(\lambda, \theta)$ is applied, which is zero over land and
 690 unity over the ocean. The term $\frac{\Delta V}{g}$ is a uniform shift of the geoid, added to conserve the
 691 mass of the global surface loading distribution δT

$$692 \quad \int_{\Omega} \delta T(\lambda', \theta', t) d\omega = \int_{\Omega} (\delta s(\lambda', \theta', t) + \delta h(\lambda', \theta', t)) d\omega = 0. \tag{A2}$$

693 In the spectral domain, and using linearized Euler equations, we can express Eq.(A1) in
 694 a matrix notation

$$695 \quad \tilde{S} = \mathbf{G}_{N-U}^L (\mathbf{O}\tilde{S} + \vec{H}) + \mathbf{G}_{N-U}^T \mathbf{\Xi} (\mathbf{O}\tilde{S} + \vec{H}). \tag{A3}$$

696 Eq. (A3) is linear in \tilde{S} and can thus be solved by inversion:

$$697 \quad \tilde{S} = (\mathbf{1} - \mathbf{G}_{N-U}^L \mathbf{O} - \mathbf{G}_{N-U}^T \mathbf{\Xi} \mathbf{O})^{-1} (\mathbf{G}_{N-U}^L + \mathbf{G}_{N-U}^T \mathbf{\Xi}) \vec{H}. \tag{A4}$$

698 The vectors \tilde{S} and \vec{H} contain the (stacked) spherical harmonic coefficients of the sea
 699 level and the load distribution; \mathbf{G}_{N-U}^L and \mathbf{G}_{N-U}^T are the matrix representations of the
 700 Green's Functions G_{N-U}^L and G_{N-U}^T . Multiplication with matrix \mathbf{O} represents the spectral
 701 convolution with the ocean function. Due to the relatively short time period of seven years
 702 considered in this study \mathbf{O} is assumed to be time-independent. The matrix Ξ converts
 703 the changes of the surface loading into rotational potential changes.

704 The vector \tilde{S} is the quasi-spectral sea level and represents an equipotential surface shifted
 705 by a uniform constant. To obtain the sea level \vec{S} which is zero over land (and not an
 706 equipotential surface), the ocean function has to be applied

$$\vec{S} = \mathbf{O}\tilde{S}. \quad (\text{A5})$$

708 The Green's functions \mathbf{G}_{N-U}^L and \mathbf{G}_{N-U}^T are only defined for degrees larger than zero.
 709 Thus we augment the spectral representation of the sea level equation by a degree zero
 710 term which ensures mass conservation according to

$$\vec{S}_{00} = -\vec{H}_{00} = \sum_{n=0}^{n_{max}} \sum_{m=-n}^n O_{nm} \tilde{S}_{nm}. \quad (\text{A6})$$

A2. Green's functions

712 Assuming a spherical, non-rotating, elastic and isotropic Earth, the matrices \mathbf{G}_{N-U}^L and
 713 \mathbf{G}_{N-U}^T are diagonal and depend on the load Love numbers h'_n , k'_n and body Love numbers
 714 h_n , k_n , respectively:

$$\mathbf{G}_{N-U}^L = \text{diag} \left\{ \frac{3\rho_w}{(2n+1)\rho_e} (1 + k'_n - h'_n) \right\}, \quad n > 0, \quad (\text{A7})$$

716 with ρ_w and ρ_e being the density of sea water and the mean density of the solid Earth,
717 and

$$718 \quad \mathbf{G}_{N-U}^T = \text{diag} \left\{ \frac{1}{g} (1 + k_n - h_n) \right\}, \quad n > 0. \quad (\text{A8})$$

A3. Rotational feedback

719 The matrix Ξ for mapping surface loading changes to rotational potential can be splitted
720 into a product of three (sparse) matrices

$$721 \quad \Xi = \underset{\Lambda \leftarrow m}{\Phi} \quad \underset{m \leftarrow J}{\Gamma} \quad \underset{J \leftarrow T}{\Psi}. \quad (\text{A9})$$

722 The matrix $\underset{J \leftarrow T}{\Psi}$ converts the degree 2 surface loading coefficients T_{2m} to the corresponding
723 moments of inertia J_i^R of the rigid Earth, neglecting higher order moments of inertia [*Milne*
724 *and Mitrovica*, 1998]

$$725 \quad \begin{pmatrix} \delta J_1^R \\ \delta J_2^R \\ \delta J_3^R \end{pmatrix} = \pi a^4 \rho_w \begin{pmatrix} 0 & 0 & -\frac{4}{5} \sqrt{\frac{10}{6}} & 0 \\ 0 & 0 & 0 - \frac{4}{5} \sqrt{\frac{10}{6}} & 0 \\ \frac{8}{3} & -\frac{8}{3\sqrt{5}} & 0 & 0 \end{pmatrix} \begin{pmatrix} T_{00} \\ T_{20} \\ T_{2,1} \\ T_{2,-1} \end{pmatrix}. \quad (\text{A10})$$

726 Here, a is the mean radius of the Earth. Changes in the moments of inertia J_i^R are linked
727 to the polar motion m with the matrix $\underset{m \leftarrow J}{\Gamma}$ [*Mitrovica et al.*, 2005]

$$728 \quad \begin{pmatrix} m_1 \\ m_2 \\ m_3 \end{pmatrix} = \begin{pmatrix} \Omega \frac{1+k'_2}{A\sigma_0} & 0 & 0 \\ 0 & \Omega \frac{1+k'_2}{A\sigma_0} & 0 \\ 0 & 0 & -\frac{1+k'_2}{C} \end{pmatrix} \begin{pmatrix} \delta J_1^R \\ \delta J_2^R \\ \delta J_3^R \end{pmatrix}, \quad (\text{A11})$$

729 where Ω is the mean angular frequency of the Earth, A and C are the Earth's principal
 730 moments of inertia and σ_0 is the Chandler frequency. Finally, a change of the polar motion
 731 has a feedback on the rotational potential Λ , expressed with the matrix $\Phi_{\Lambda \leftarrow m}$ [Milne and
 732 Mitrovica, 1998]

$$733 \begin{pmatrix} \Lambda_{00} \\ \Lambda_{20} \\ \Lambda_{2,1} \\ \Lambda_{2,-1} \end{pmatrix} = (a\Omega)^2 \begin{pmatrix} 0 & 0 & \frac{2}{3} \\ 0 & 0 & -\frac{2}{3\sqrt{5}} \\ -\frac{1}{\sqrt{15}} & 0 & 0 \\ 0 & -\frac{1}{\sqrt{15}} & 0 \end{pmatrix} \begin{pmatrix} m_1 \\ m_2 \\ m_3 \end{pmatrix}. \quad (\text{A12})$$

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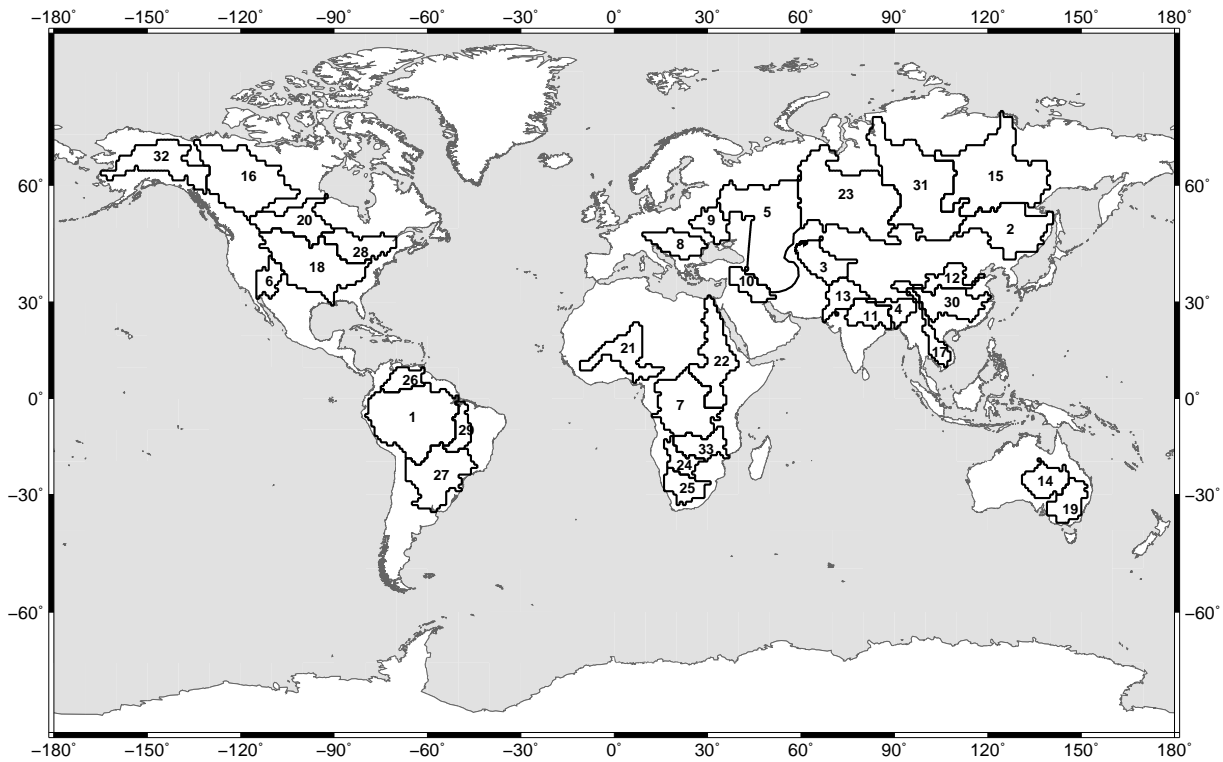


Figure 1: Outlines of the 33 world's largest river basins considered in this study (black lines). The outlines of the three biggest ocean basins (used in section 4.2) are depicted in dark grey (Indian Ocean), middle grey (Atlantic Ocean) and light grey (Pacific Ocean).

Table 1: Trend of mass variations [Gt/yr] from 33 basins for 08/2002 to 07/2009.^a

No.	Name	BasAv	InvGR	Inv	InvEOF	WGHM
1	Amazon	101.9	82.7	67.2	67.0	90.4
2	Amur	-5.6	-7.6	-6.2	-1.7	2.7
3	Aral	-14.5	-1.1	-3.3	3.4	-2.0
4	Brahmaputra	-12.4	5.7	4.8	3.4	1.1
5	Caspian-Volga	-24.9	-18.0	-18.3	1.4	-17.1
6	Colorado	-2.0	-13.4	-14.5	-13.9	-1.4
7	Congo	2.8	19.2	13.6	10.7	40.1
8	Danube	2.7	-3.8	-6.2	-5.7	-0.7
9	Dnepr	-1.1	5.7	6.1	2.8	-1.1
10	Euphrates	-19.9	-19.4	-20.5	-21.0	-6.0
11	Ganges	-22.6	-16.7	-15.9	-18.1	-16.0
12	Huanghe	-3.2	-14.8	-13.8	-15.5	-3.4
13	Indus	-17.3	-1.8	-2.2	-5.7	2.1
14	Lake-Eyre	-6.6	-7.1	-7.7	-5.4	0.4
15	Lena	19.9	24.3	25.1	10.6	11.1
16	Mackenzie	-3.0	-18.5	-18.9	1.3	7.6
17	Mekong	0.0	-9.9	-8.0	-5.3	0.6
18	Mississippi	3.0	-14.6	-17.6	-19.1	5.9
19	Murray	-7.3	-8.5	-9.8	-12.2	0.1
20	Nelson	-8.4	-1.9	-2.2	-6.7	15.0
21	Niger	10.3	25.7	20.1	24.5	1.7
22	Nile	25.8	26.9	21.6	24.8	8.4
23	Ob	-1.8	18.1	17.3	9.9	3.8
24	Okavango	14.0	21.9	19.9	17.3	5.6
25	Orange	2.9	-8.0	-9.8	-6.0	0.9
26	Orinoco	16.0	31.2	28.0	21.7	10.2
27	Parana	-4.8	-4.3	-14.9	12.3	-8.9
28	St-Lawrence	4.4	4.4	5.6	8.1	8.7
29	Tocantins	4.8	7.0	6.4	9.2	-0.4
30	Yangtze	13.8	19.5	21.1	17.6	-4.3
31	Yenisei	23.5	-0.1	1.3	13.4	6.4
32	Yukon	-21.0	-56.8	-56.3	-61.0	1.5
33	Zambezi	20.4	10.7	9.6	12.4	2.8
	TOTAL	89.7±16.4	76.8±1.4	21.6±1.5	74.7±1.4	165.7
	Mean Rel. Diff. [%]		62.5	63.1	70.8	79.4
	Rel.Diff. Total [%]		14.4	75.9	16.7	45.9

^a *BasAv* indicates the results obtained with a GRACE basin averaging method. *InvGR*

indicates the results obtained with the fingerprint inversion method, using only GRACE data (GIA scale fixed to 1.0). *Inv* indicates the results of the multisensor fingerprint inversion using GRACE and Jason-1 data (GIA scale fixed to 1.0). *InvEOF* is our 'best estimate' from the fingerprint inversion using GRACE and Jason-1 and EOF WGHM

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fingerprints (two for Amazon basin, one for the others) for the terrestrial hydrological

changes (GIA scale co-estimated). *WGHM* are the trends obtained from the WGHM.

Table 2: Annual amplitude of mass variations [Gt] from 33 basins for 08/2002 to 07/2009.^a

No.	Name	BasAv	InvGR	Inv	InvEOF	WGHM
1	Amazon	1171.0 (4.4)	1312.5 (4.8)	1306.1 (4.7)	1207.0 (4.8)	520.1 (3.7)
2	Amur	48.6 (4.6)	34.9 (4.2)	30.0 (4.2)	1.9 (6.2)	14.8 (0.4)
3	Aral	91.9 (4.1)	77.9 (5.6)	79.2 (5.4)	77.4 (5.1)	27.3 (2.9)
4	Brahmaputra	126.5 (8.4)	266.5 (8.8)	261.5 (8.8)	240.4 (9.0)	65.0 (8.5)
5	Caspian-Volga	228.1 (4.0)	268.5 (4.3)	267.3 (4.2)	236.4 (3.7)	198.8 (2.5)
6	Colorado	35.8 (3.2)	29.8 (2.8)	37.4 (2.3)	50.3 (3.1)	8.0 (1.8)
7	Congo	171.8 (2.3)	163.7 (2.6)	201.6 (2.5)	287.7 (3.5)	88.1 (2.0)
8	Danube	62.8 (3.3)	65.5 (3.0)	64.5 (3.0)	80.1 (2.6)	56.8 (2.4)
9	Dnepr	52.9 (3.5)	120.5 (3.7)	115.6 (3.7)	85.9 (4.0)	38.8 (2.3)
10	Euphrates	71.2 (3.9)	164.6 (4.0)	167.4 (4.0)	156.8 (4.1)	24.6 (2.5)
11	Ganges	172.7 (9.5)	282.4 (10.6)	280.3 (10.6)	210.7 (10.5)	91.4 (9.0)
12	Huanghe	18.5 (10.9)	74.5 (1.3)	71.6 (1.3)	49.9 (1.5)	13.3 (9.1)
13	Indus	29.0 (4.1)	55.6 (7.2)	52.8 (7.1)	42.8 (5.7)	10.6 (3.8)
14	Lake-Eyre	5.7 (11.2)	51.8 (4.0)	64.5 (3.8)	88.1 (4.1)	4.1 (2.1)
15	Lena	117.2 (3.3)	203.1 (3.6)	199.2 (3.5)	160.5 (3.6)	89.2 (2.7)
16	Mackenzie	109.1 (3.5)	78.7 (3.7)	80.5 (3.5)	49.3 (3.2)	86.7 (2.9)
17	Mekong	226.8 (9.5)	452.8 (10.6)	444.0 (10.6)	358.9 (10.7)	87.7 (8.8)
18	Mississippi	207.6 (3.9)	301.5 (3.9)	306.1 (3.7)	273.5 (3.6)	147.5 (2.7)
19	Murray	38.6 (9.3)	82.4 (7.4)	67.4 (7.1)	52.0 (7.4)	11.5 (8.8)
20	Nelson	45.4 (4.2)	53.6 (3.5)	56.1 (3.3)	85.0 (3.5)	37.0 (2.6)
21	Niger	221.8 (9.5)	383.9 (10.0)	368.4 (10.2)	430.5 (10.4)	86.2 (9.3)
22	Nile)	215.1 (9.7)	247.9 (10.3)	241.5 (10.5)	192.7 (10.4)	81.2 (8.8)
23	Ob)	200.8 (3.7)	219.1 (3.9)	224.8 (3.8)	159.6 (4.0)	176.9 (2.7)
24	Okavango	62.6 (3.7)	19.9 (10.3)	19.2 (11.5)	23.8 (0.3)	18.2 (2.5)
25	Orange	12.7 (4.7)	46.1 (7.8)	20.1 (7.5)	18.8 (8.6)	4.5 (2.1)
26	Orinoco	211.0 (8.7)	295.3 (9.3)	293.0 (9.4)	195.0 (10.0)	99.2 (8.8)
27	Parana	162.4 (3.7)	137.5 (4.5)	151.5 (4.0)	197.6 (4.0)	93.7 (2.9)
28	St-Lawrence	76.0 (3.6)	116.3 (2.9)	117.3 (2.8)	110.6 (2.8)	89.6 (2.8)
29	Tocantins	326.8 (3.9)	396.0 (4.4)	396.5 (4.3)	371.7 (4.7)	117.1 (3.5)
30	Yangtze	95.3 (7.8)	102.6 (8.7)	107.3 (8.7)	103.3 (8.8)	80.8 (8.1)
31	Yenisei	153.5 (3.0)	144.6 (3.5)	137.7 (3.5)	154.7 (3.7)	129.1 (2.8)
32	Yukon	88.9 (3.2)	120.9 (3.5)	118.2 (3.5)	91.3 (3.7)	47.5 (2.8)
33	Zambezi	239.9 (3.7)	459.9 (4.3)	468.8 (4.2)	357.4 (4.2)	71.2 (2.9)
Amp.	TOTAL	2478.1±214.1	2375.6±18.0	2468.7±22.5	2442.6±20.4	1406.8
Pha.	TOTAL	4.20±0.04	4.25±0.01	4.14±0.01	4.14±0.01	3.02
Amp.	Mean Diff. [%]		33.9	32.5	32.1	44.5
Amp.	Diff. Total [%]		4.1	0.4	1.4	43.2
Pha.	RMSE [mn]		0.29	0.27	0.26	0.27
Pha.	Diff. Total [mn]		0.05	-0.05	-0.06	-1.17

^a The numbers in brackets give the time in the year (in months) when the maximum of the annual variation is reached (phase).

Table 3: Trend of terrestrial hydrological mass variations [Gt/yr] accumulated over the continents for 08/2002 to 07/2009.

	BasAv	InvGR	Inv	InvEOF	WGHM
South America	117.8	116.5	86.7	110.2	91.3
North America	-27.0	-100.8	-104.0	-91.3	37.2
Africa	76.2	96.4	75.0	83.6	59.5
Eurasia	-63.3	-19.8	-18.6	-10.3	-22.7
Australia	-14.0	-15.5	-17.5	-17.6	0.5
Mean Rel.Diff [%]		34.8	38.6	38.0	76.9

Table 4: global mean sea level contributions, estimated from GRACE and Jason-1 for 08/2002 to 07/2009.^a

	Global mean sea level trend [mm/yr]	Mean sea level trend for latitude < 66 ° [mm/yr]
Greenland	0.63 ± 0.008	0.67 ± 0.008
Antarctica	0.26 ± 0.014	0.27 ± 0.014
Glaciers	0.58 ± 0.027	0.61 ± 0.027
Hydrology	-0.20 ± 0.037	-0.20 ± 0.037
Steric	0.35 ± 0.022	0.37 ± 0.022
GIA	-0.16 ± 0.003	-0.16 ± 0.003
TOTAL (explained)	1.45 ± 0.053	1.56 ± 0.053
TOTAL (Jason-1)		1.94 ± 0.0046

^a Please note that the standard deviation of 0.0046 mm/yr for the Jason-1 trend should be interpreted as an instrument-related accuracy propagated to global mean sea level change, which does not account, e.g., for mesoscale current variability and steric sea level change beyond the large-scale pattern we impose in the inversion. In contrast, our inversion misfit of 0.3-0.4 mm/yr suggests that these effects clearly dominate over the instrumental errors in altimetry.

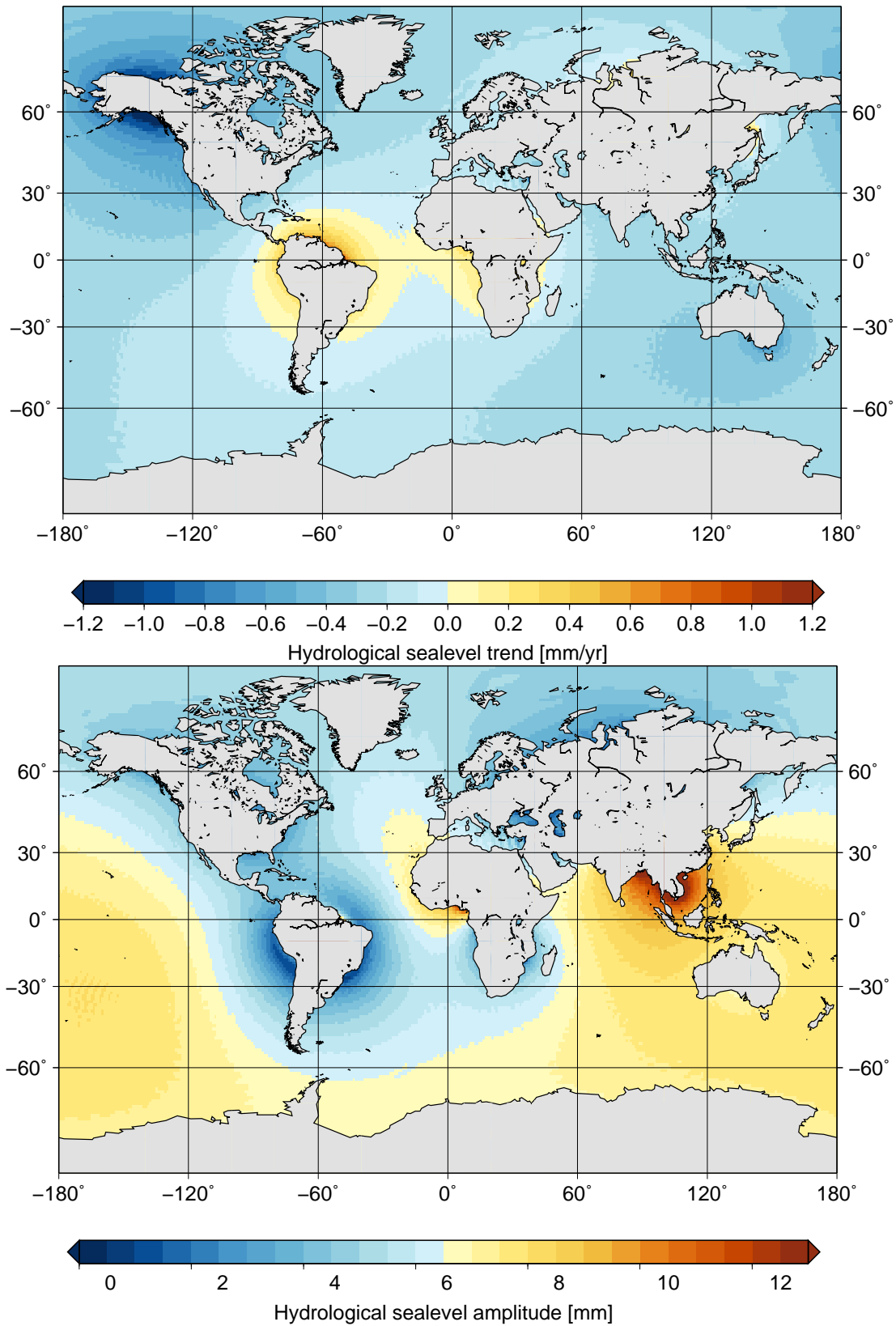


Figure 2: Global sealevel trend and annual amplitude induced by terrestrial hydrological cycle mass changes calculated with a joined inversion of GRACE and Jason-1 data for

Table 5: Average regional sea level from terrestrial hydrological cycle changes, estimated from GRACE and Jason-1 for 08/2002 to 07/2009.

	Sea level trend [mm/yr]	Annual amplitude[mm]
Atlantic Ocean	-0.06	5.56
Pacific Ocean	-0.25	6.94
Indian Ocean	-0.23	7.55